

XRAY X4'24'

The diagram illustrates the top-down layout of a robot chassis. Key components and their selection options are as follows:

- FRONT BOTTOM VIEW**: This label is positioned at the top center of the diagram.
- STEER. LOCK**: A callout pointing to the steering lock mechanism on the left side, with a selection table:

18	/degr.
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- T-BRACE**: A callout pointing to the T-brace on the right side, with a selection table:

ALU	<input type="checkbox"/>
BRASS	<input type="checkbox"/>
- SERVO HOLDER**: A callout pointing to the servo holder in the center, with a selection table:

FR	<input type="checkbox"/>
RE	<input type="checkbox"/>
- MOTOR MOUNT**: A callout pointing to the motor mount in the center, with a selection table:

GRAPHITE	<input type="checkbox"/>
ALU	<input checked="" type="checkbox"/>
ALU 1.5mm	<input type="checkbox"/>
- CHASSIS**: A callout pointing to the main chassis body, with a selection table:

GRAPHITE	<input type="checkbox"/>
ALU	<input checked="" type="checkbox"/>
ALU 1.5mm	<input type="checkbox"/>
- FRONT ARMS**: A callout pointing to the front arms on the left, with a selection table:

MEDIUM	<input type="checkbox"/>
HARD	<input checked="" type="checkbox"/>
- REAR ARMS**: A callout pointing to the rear arms on the right, with a selection table:

MEDIUM	<input type="checkbox"/>
HARD	<input checked="" type="checkbox"/>