

XRAY X4'24'

The diagram illustrates the chassis assembly from three perspectives: FRONT, BOTTOM VIEW, and REAR. Key components and their assembly instructions are as follows:

- FRONT VIEW:** Shows the front suspension arms and steering mechanism. A servo is mounted in the **SERVO HOLDER** with the horn pointing **FR** (Forward). The **STEER. LOCK** is set to **23 /degr.**
- BOTTOM VIEW:** Shows the underside of the chassis. The **MOTOR MOUNT** is centered. The **FRONT ARMS** are attached to the chassis. The **REAR ARMS** are also attached. The **CHASSIS T-BRACE** is shown connecting the rear arms.
- REAR VIEW:** Shows the rear suspension and motor area. The **T-BRACE** is attached to the **ALU BRASS** plate. The **CHASSIS T-BRACE** is also shown.
- CHASSIS:** The main body of the robot. It has a **GRAPHITE** plate on top, an **ALU** plate, and an **ALU 1.5mm** plate. The **FRONT ARMS** are attached to the chassis. The **REAR ARMS** are also attached. The **CHASSIS T-BRACE** is shown connecting the rear arms.
- FRONT ARMS:** Two arms attached to the front of the chassis. They are made of **MEDIUM** or **HARD** material. The **MEDIUM** option is selected with a red 'X' in the box.
- REAR ARMS:** Two arms attached to the rear of the chassis. They are made of **MEDIUM** or **HARD** material. The **MEDIUM** option is selected with a red 'X' in the box.