

XRAY X4'23

The diagram illustrates the assembly options for the robot chassis, divided into three main views: FRONT, BOTTOM VIEW, and REAR.

FRONT VIEW:

- STEER. LOCK:** A box with the value **25** and the unit **/deg.**
- STEER. SHIM:** A box with the label **SIZE** and the unit **/mm**.
- FRONT BRACE:** A box with the label **YES** and two checkboxes, one of which is marked with a red 'X'.
- SERVO HOLDER:** A box with the labels **FR** and **RE**, each followed by a red dot and a circle.
- FRONT ARMS:** A box with the labels **MEDIUM** and **HARD**, each followed by a checkbox. The **MEDIUM** checkbox is marked with a red 'X'.

BOTTOM VIEW:

- MOTOR MOUNT:** A box with the label **GRAPHITE** and a red 'X' in a box, and the label **ALU FLEX** and a checkbox.
- CHASSIS:** A box with the label **GRAPHITE** and a red 'X' in a box, and the label **ALU FLEX** and a checkbox.

REAR VIEW:

- T-BRACE:** A box with the labels **ALU** and **BRASS**, each followed by a checkbox.
- CHASSIS T-BRACE:** A box with the label **CHASSIS T-BRACE** and a checkbox.
- REAR ARMS:** A box with the labels **MEDIUM** and **HARD**, each followed by a checkbox. The **MEDIUM** checkbox is marked with a red 'X'.